



Linux DMA from User Space

John Linn
Based on Linux kernel 3.14



Prerequisites

- Knowledge of the Linux kernel in general such as building and configuring the kernel
- Character device driver experience in Linux
- Experience with the C programming language
- This session assumes you have attended previous training sessions
 - Device Driver Frameworks (TSC 2014)
 - User Space IO Drivers (TSC 2014)
 - Linux DMA in Device Drivers (Part 1 of DMA series)

Review From Linux DMA In Device Drivers

- The primary components of DMA include the DMA device control, memory allocation and cache control
- DMA in Linux is designed to be used from kernel space by a higher layer device driver
- The **DMA Engine** in Linux is a framework which allows access to DMA controller drivers (such as AXI DMA) in a consistent and more abstract manner
- Xilinx provides device drivers which plug into the **DMA Engine** framework (AXI DMA, AXI CDMA, and AXI VDMA)
- Memory can be allocated using **kmalloc()** for cached memory or **dma_alloc_coherent()** for uncached memory
- DMA cache control functions such as **dma_map_single()** and **dma_unmap_single()** are used with cached memory buffers

Introduction

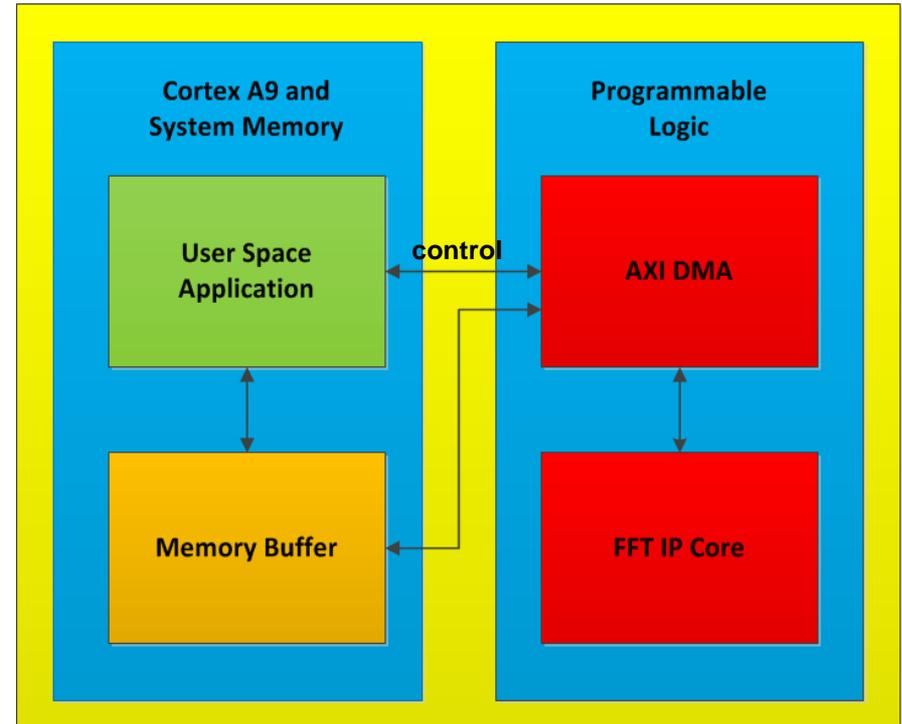
- **A challenge in Linux is doing application processing in user space while moving data to and from devices in the PL**
- **Linux provides frameworks that allow user space to interface with kernel space for most types of devices (except DMA)**
- **User Space DMA is defined as the ability to access buffers for DMA transfers and control DMA transfers from a user space application**
 - This is not an industry standard and there are a number of possible methods
 - Similar methods have been used for years with display systems such as X11, as they needed direct access to video frame buffers
- **Xilinx SDIntegrator might be an easier solution for some applications and should be considered**
 - It uses similar principles without the user implementing any code

Applications of User Space DMA

➤ A typical User Space DMA application creates data which needs to be transferred from the CPU memory to/from a custom IP core

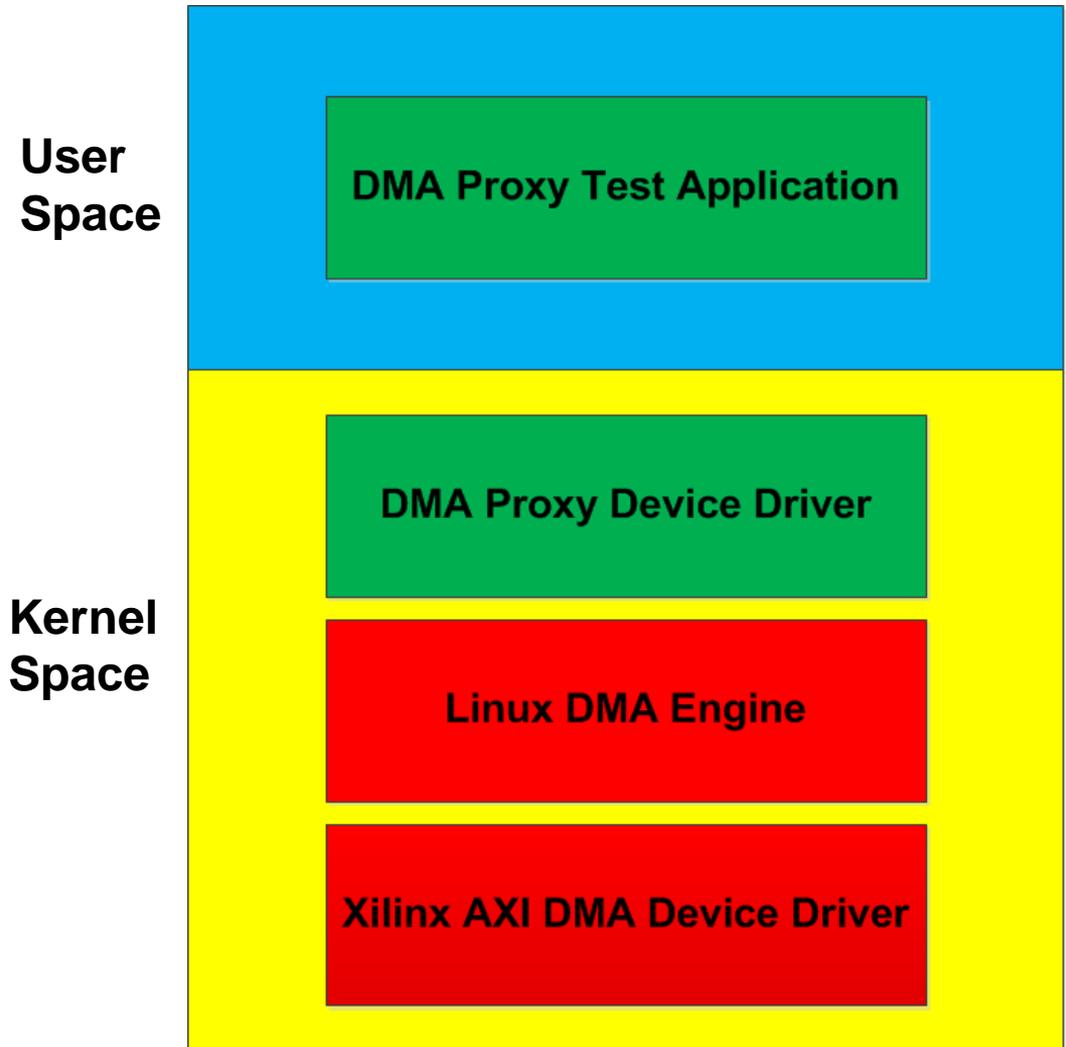
Examples

- FFT IP core processing a block of data
- Custom IP Core generating blocks of data
- See the Spectrum Analyzer Tech Tip



User Space DMA Software Example (High Level)

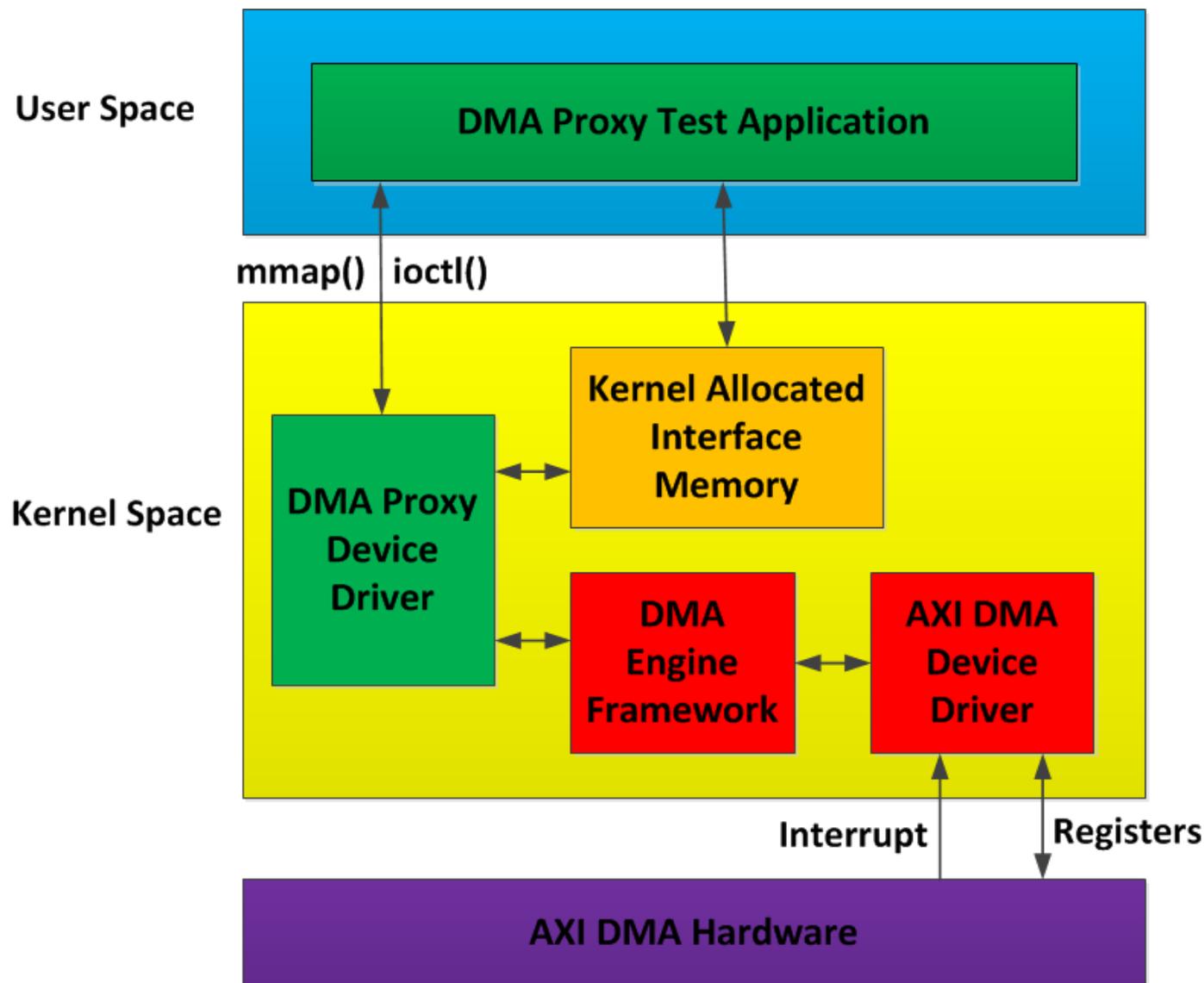
- The software design is made up of a kernel space device driver and a user space application
- The **Xilinx AXI DMA Device Driver** and **Linux DMA Engine** exist in the Linux kernel
- The **DMA Proxy Device Driver** is a character device driver that uses the Linux DMA Engine
- The **DMA Proxy Test Application** uses the DMA Proxy Device Driver to control DMA transfers



Key Learning For The Session

- Creation of a character device driver that extends the functionality of the DMA kernel driver from the Linux DMA in Device Drivers session
- Creation of a user space application that uses the character device driver to perform DMA transfers
- Implementation of `ioctl()` in the device driver and in the user space application to cause the DMA Engine to perform DMA transfers
- Implementation of `mmap()` in the device driver and in the user space application to map kernel allocated memory into user space process address space
- These principles should work across any DMA device that is supported by the Linux DMA Engine

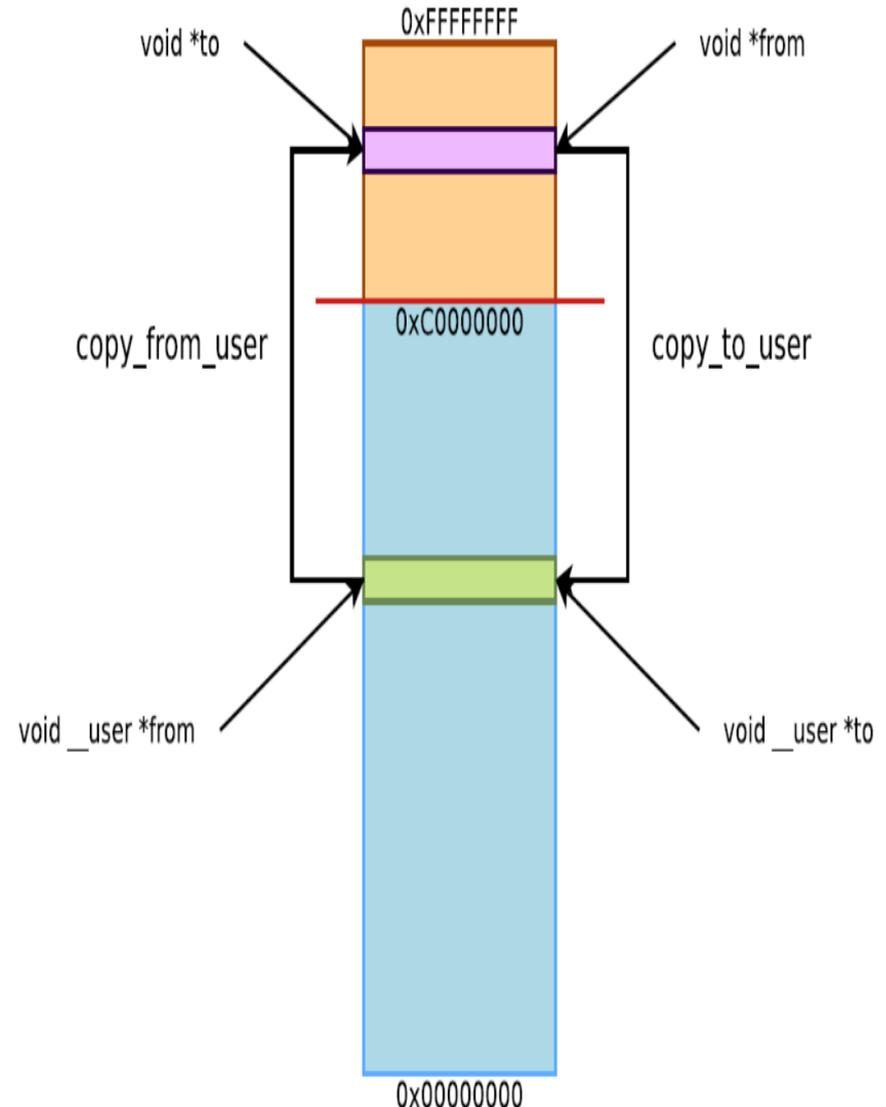
DMA Proxy Software Detailed Design



Copying Data Between Kernel and User Space

Review

- Moving data between userspace and kernel space is the primary method for I/O since the application is in userspace and the device drivers are in kernel space
- The `copy_to_user()` function copies a buffer of bytes from kernel space to userspace
- The `copy_from_user()` function copies a buffer of bytes from userspace to kernel space
- Functions also exist for copying a single datum



Zero Copy Buffer Design

- Many software designs copy data from user space to kernel space and from kernel space to user space
- For larger buffers copying data is inefficient and in the case of DMA it defeats the purpose of using DMA to move the data
- A zero copy design avoids copying memory and is required for user space DMA applications
- Some network stacks (not Linux) provide a zero copy design and achieve higher performance
- Mapping a kernel space allocated memory buffer into user space removes the need to copy data
- Mapping user space allocated buffers into kernel space so that a driver can access them is another method
 - This is more complex and not covered in this session

Character Device Framework Review

- The **character device framework** of Linux provides functionality such as **open()**, **read()**, **write()** and **close()** which allows a device driver to be accessed using the file I/O operations from user space
- It also provides the **ioctl()** interface which is used to control the device in non standard ways
- The function prototype in a driver:
 - `int (*ioctl) (struct inode *inode, struct file *filp, unsigned int cmd, unsigned long arg);`
- The **cmd** and **arg** arguments are passed from user space to the driver unchanged such that they are easily used for control
- The **ioctl()** function of the device driver can perform any functionality including blocking until the functionality is complete

Controlling The Kernel Space Driver

- The user space application needs to control the kernel space driver to allow DMA transactions to be managed
- The `read()` and `write()` file operations could easily be used
 - These do offer the ability to do asynchronous (non-blocking) I/O using `poll()` and `select()` functions
- The `ioctl()` file operation is designed for device control and is used to control the DMA Proxy device driver for simplicity
- The `mmap()` file operation allows memory of the device driver to be mapped into the address space of the caller in a user space process
- The **UIO driver framework** provides another alternative for this design which is simpler but limited and less flexible
 - `mmap()` can be overridden with your own implementation for non-cached memory
 - It's not as flexible as the character device framework

The Character Device Driver Simplified Example

```
int dma_proxy_open() { };
int dma_proxy_ioctl() { };
int dma_proxy_mmap() { };
int dma_proxy_release() { };

static struct file_operations dma_proxy_fops =
{
    .owner          = THIS_MODULE,
    .open           = dma_proxy_open,
    .unlocked_ioctl = dma_proxy_ioctl,
    .mmap           = dma_proxy_mmap,
    .release        = dma_proxy_release,
};

int dma_proxy_init()
{
    struct cdev cdev;
    cdev_init(&cdev, &dma_proxy_fops);
    cdev_add(&cdev, ....);
}
```

- Create empty file operation functions `dma_proxy_open()`, `dma_proxy_ioctl()`, `dma_proxy_mmap()`, & `dma_proxy_release()`
- Create the `file_operations` data structure `dma_proxy_fops`
- The driver `dma_proxy_init()` function calls the character device functions to create the character device
- The `cdev_init()` function initializes the character device including setting up the file functions such as `dma_proxy_ioctl()`
- The `cdev_add()` function connects the character device to the kernel

Cached Buffers Considerations

- **Cache control from user space is challenging and less obvious**
 - Cache control is done in the DMA Proxy device driver from kernel space
- **Many people would assume that using caches makes everything faster**
 - It depends on how the application uses the data and the data size
 - Caching large buffers can pollute the CPU cache, causing other system impacts
- **The cache operations required for a DMA driver do take time for the CPU**
- **An application which only controls a DMA transfer without touching any of the data can use uncached memory**
- **The amount of memory that can be allocated varies for cached and uncached memory**
 - 4 MB cached memory using [kmalloc\(\)](#) or [get_free_pages\(\)](#)
 - Configurable (much larger) with uncached memory using [dma_alloc_coherent\(\)](#) and the contiguous memory allocator in Linux

Details of Controlling DMA From User Space

- **Shared memory between user space and kernel space can be used for more than data buffers**
- **Control and status in addition to data is needed from user space**
- **Control of the DMA includes the ability to:**
 - start/stop a transaction
 - a source address for the data buffer
 - a length specifying how many bytes of data are in the data buffer
- **Status of the DMA includes the ability to see that the transfer completed and any errors that might have occurred**
- **The DMA Proxy example uses kernel allocated memory referred to as interface memory**

Interface Memory Details

- The interface memory is allocated by the DMA proxy driver and mapped to user space using `mmap()`
- The `dma_proxy_channel_interface` contains the data, control and status for a channel
- The user space application controls the DMA proxy driver using the data in the interface memory
- The DMA proxy device driver controls the DMA Engine using the data in the interface memory

DMA Proxy Channel Interface



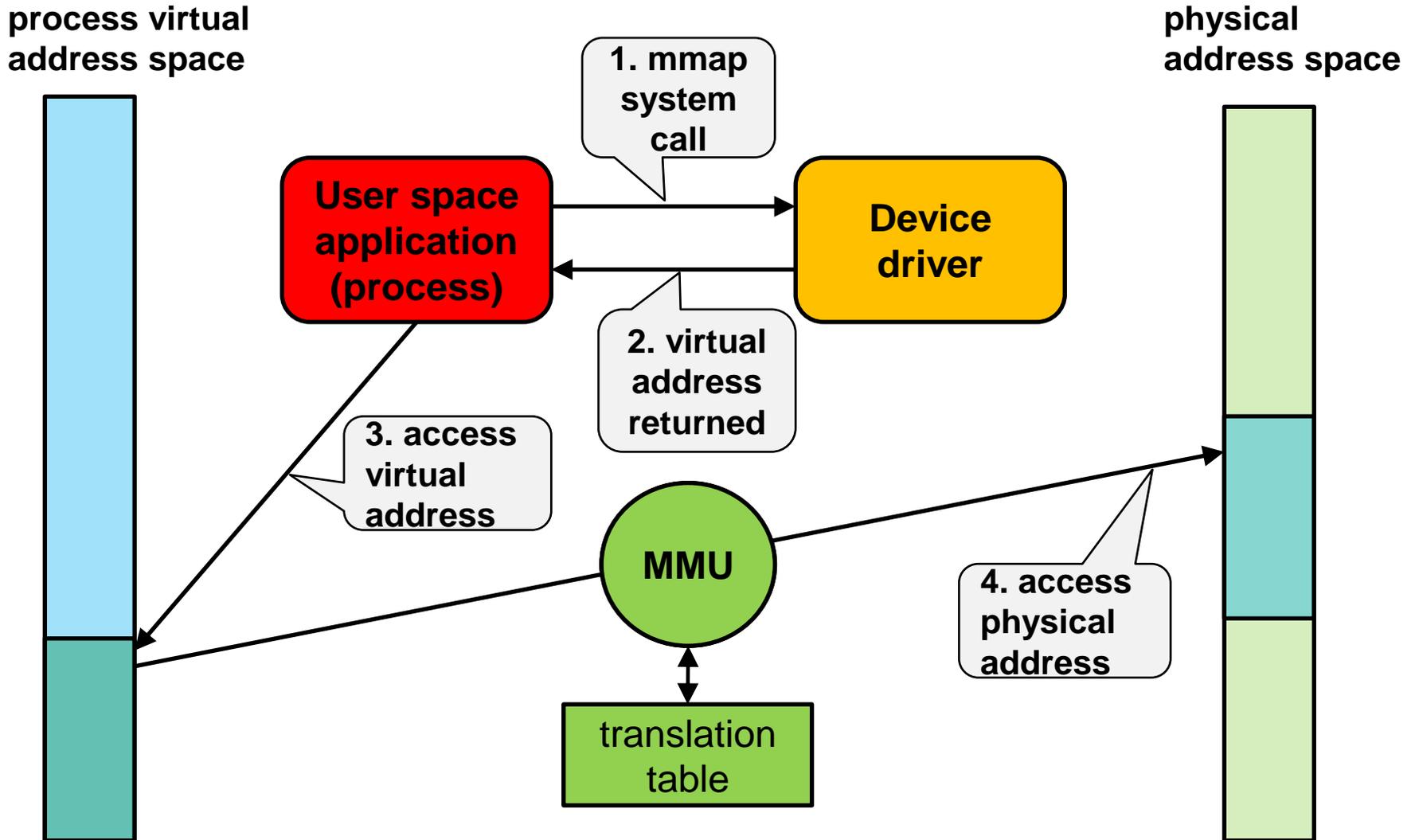
```
struct dma_proxy_channel_interface {  
    unsigned char buffer[32 * 1024 * 1024];  
    enum proxy_status {  
        PROXY_NO_ERROR = 0, PROXY_BUSY = 1,  
        PROXY_TIMEOUT = 2, PROXY_ERROR = 3  
    } status;  
    unsigned int length;  
};
```

Note the buffer is the first member of the struct to ensure it is cache line aligned.

Introduction to Mapping Memory with mmap()

- The character device driver framework of Linux provides the ability to map memory into a user space process address space
- A character driver must implement the `mmap()` function which a user space application can call
- The `mmap()` function creates a new mapping in the virtual address space of the calling process
 - A virtual address, corresponding to the physical address specified, is returned
 - `mmap()` can also be used to map a file into a memory space such that the contents of the file are accessed by memory reads and writes
- Whenever the user space program reads or writes in the virtual address range it is accessing the device
- This provides improved performance as no system calls are required

Mapping Device Memory Flow



Details of Mapping Memory with `mmap()`

➤ Calling `mmap()` from the user space application

- The call to `mmap()` requires an address and size for the memory being mapped into user space
- The application passes zero for the address to map, since it doesn't know the address of the buffer allocated in the kernel driver
- The size cannot be zero as `mmap()` will return an error
- The application knows the size using a shared data definition in a header file

➤ Implementing `mmap()` in the kernel space device driver

- The `mmap()` function in the driver must alter the caching attributes to match the kernel buffer being mapped if the buffer is not cached
 - Memory allocated with `kmalloc()` is cached
- The DMA framework provides a `mmap()` function which can be called from the driver `mmap()` function to perform the memory mapping for buffers allocated from the DMA framework
 - Memory allocated with `dma_alloc_coherent()` is uncached

Simple User Space Application Example

```
struct dma_proxy_channel_interface { }

void main() {
    struct dma_proxy_channel_interface *proxy_interface_p;
    int proxy_fd;

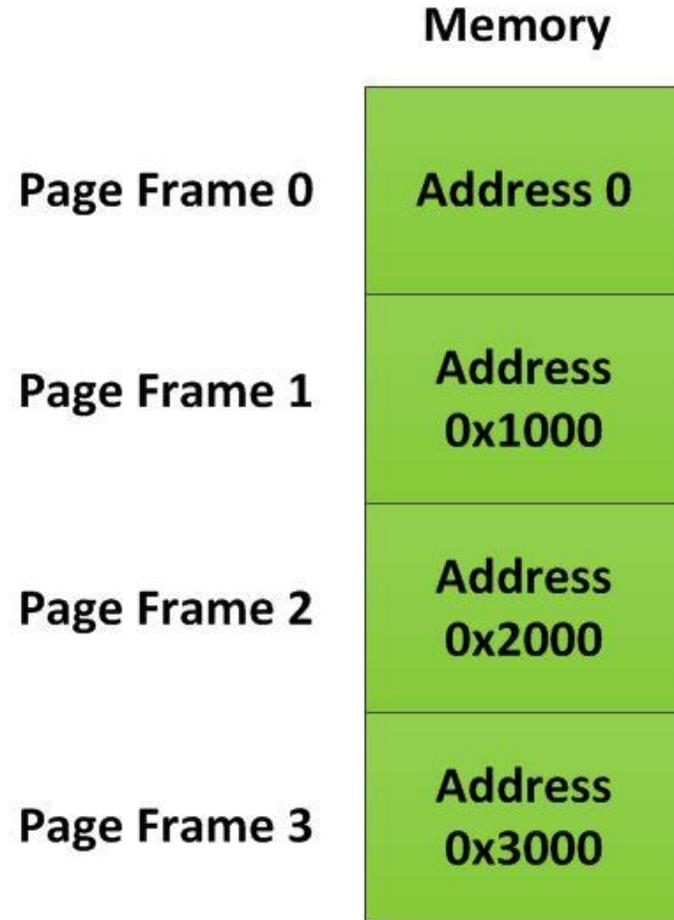
    proxy_fd = open("/dev/dma_proxy", O_RDWR);
    proxy_interface_p = mmap(0, sizeof(dma_proxy_channel_interface),
        PROT_READ | PROT_WRITE, MAP_SHARED, proxy_fd, 0);
}
```

The device file causes the mmap() function to run in the driver

- Start with an empty main() function and a defined channel interface data type
- Open the device file for the DMA proxy
- Call the mmap() function to map the kernel allocated buffer into the process address space
- The first argument is the physical memory address to map into the virtual address space
- The second argument is the size of the memory range to map

Linux Pages and Page Frame Numbers

- Virtual and physical memory are divided into handy sized units called *pages*
- These pages are all the same size, 4KB for ARM and MicroBlaze
- A page frame number is simply an index within physical memory that is counted in page-sized units
- The page frame number for a physical address can be created using the constant `PAGE_SHIFT`
`page_frame_number =`
`physical_address >> PAGE_SHIFT`



Simple Memory Mapping Driver Example

```
static int dma_proxy_mmap(struct file *filp, struct vm_area_struct *vma)
{
    if (remap_pfn_range(vma, vma->vm_start,
                       virt_to_physical(buffer_pointer) >> PAGE_SHIFT,
                       vma->vm_end - vma->vm_start,
                       vma->vm_page_prot))
        return -EAGAIN;
    return 0;
}
```

Convert the physical address to the page frame number

Note: This is for memory allocated with `kmalloc()`

- Start with an empty `mmap()` function with the expected Linux interface
- The `remap_pfn_range()` function is the easy way to implement the `mmap()` function
- Only one argument has to be created as all others come in the `vma` structure
- The 3rd argument is the **page frame number** which is based on the physical address
- The `mmap()` call from user space passes a zero for the physical address as it does not know the physical address
- **Note:** `mmap()` defaults to cached memory such that the cache attributes of the `vma` match the buffer allocated from `kmalloc()`

DMA Memory Mapping Driver Example

```
static int dma_proxy_mmap(struct file *filp, struct vm_area_struct *vma)
{
    return dma_common_mmap(dma_device_pointer,
                           vma,
                           buffer_pointer,
                           physical_buffer_pointer,
                           vma->vm_end - vma->vm_start);
}
```

Pointers are virtual addresses by default

Note: This is for memory allocated with `dma_alloc_coherent()`

- Start with an empty `mmap()` function with the expected Linux interface
- The `dma_common_mmap()` function is the easy way to implement the `mmap()` function
- The `buffer_pointer` and `physical_buffer_pointer` are both returned from `dma_alloc_coherent()`

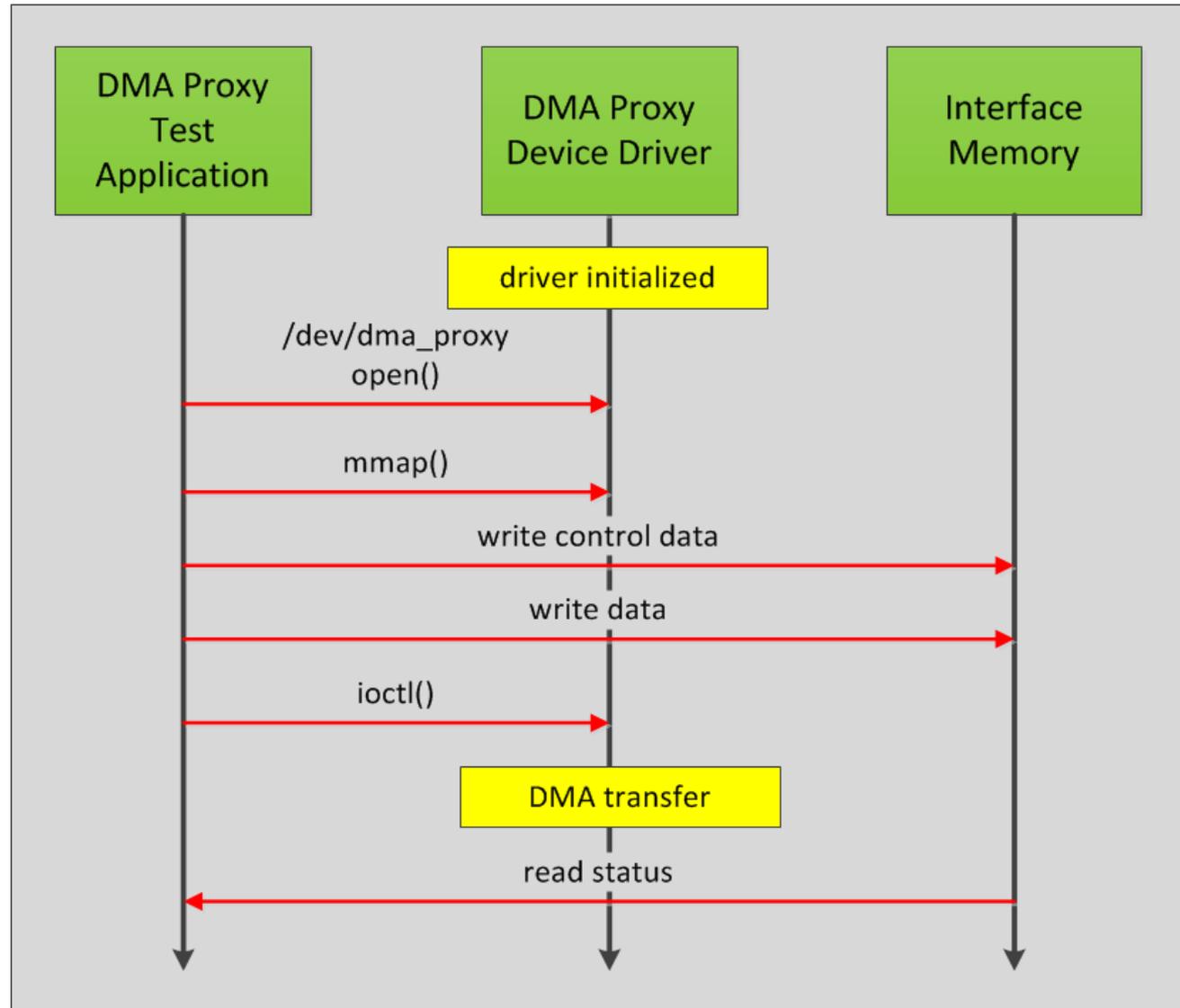
A Simple ioctl() Example Controlling DMA

```
static void transfer(struct dma_proxy_channel *pchannel_p) { };
static int open(struct inode *ino, struct file *file)
{
    file->private_data = container_of(ino->i_cdev, struct dma_proxy_channel, cdev);
    return 0;
}
static long ioctl(struct file *file, unsigned int unused1, unsigned long unused2)
{
    struct dma_proxy_channel *pchannel_p = (struct dma_proxy_channel *)file->private_data;
    transfer(pchannel_p);
    return 0;
}
```

- The **transfer()** function manages the DMA engine to cause the DMA transfer to occur
- The **transfer()** function uses the interface memory to determine the details of the DMA transaction including the length of the transfer
- The **open()** function is called when the application opens the device file
- The **ioctl()** function receives a notification requesting a DMA transfer to be performed for the device channel

Software Design Sequencing

- The diagram illustrates the interaction between the user space application, the device driver, and the interface memory with time flowing from top to bottom



Design Alternatives

- **A design which only blocks is much simpler than one that does not block**
 - Non-blocking requires asynchronous processing to complete the transaction; this is more complex
- **The DMA Buffer Sharing framework in Linux could be helpful**
 - This session is focused on the simplest example while this adds more complexity
- **It is also possible for a kernel module to get access to user space allocated memory through the `get_user_pages()` function**

Areas Of Caution for DMA

- **Memory mappings (cached, noncached, etc.) should always match for a buffer across kernel and user space**
- **Buffer alignment with respect to cache lines is needed for DMA**
- **The driver could exit and free the memory while the application is still trying to use it**
 - This is not typically an issue when the driver is built into the kernel
- **These methods have only been tested in a prototype system**
 - Not used by any customers yet
- **The performance of the DMA Engine has not been measured yet**
 - We can't really change that as it's provided in Linux
 - Being informed about performance would be prudent
 - The only alternative is using the standalone driver with UIO

Designing For Debug

- **Using interface memory to pass control to the driver rather than passing the data as arguments in ioctl() is more flexible**
- **The kernel space device driver can also alter the memory to control itself**
 - This is a good way to test the driver before the user space application is written
 - It also can help discern a working device driver from an issue with mapping memory into the user space application

Dumping Kernel Page Tables

- This feature is new to the 3.14 kernel
- The kernel page tables will show DMA allocated memory and verify it is not cached and is bufferable/write combined memory
- It can also help verify buffers are released
- Configure the kernel with **CONFIG_ARM_PTDUMP**
 - From the Kernel Hacking menu, select Export kernel pagetable
- **cat /sys/kernel/debug/kernel_page_tables**

```
---[ Kernel Mapping ]---
0xc0000000-0xc0a00000    10M    RW x  SHD
0xc0a00000-0xdf800000  494M    RW NX  SHD
0xdf800000-0xdf844000  272K    RW NX  SHD MEM/BUFFERABLE/WC
0xdf844000-0xdf900000  752K    RW NX  SHD MEM/CACHED/WBWA
0xdf900000-0xdfc01000  3076K   RW NX  SHD MEM/BUFFERABLE/WC
0xdfc01000-0xdfd00000  1020K   RW NX  SHD MEM/CACHED/WBWA
0xdfd00000-0xe0001000  3076K   RW NX  SHD MEM/BUFFERABLE/WC
0xe0001000-0xef800000 253948K RW NX  SHD MEM/CACHED/WBWA
```

A 3 MB
DMA
buffer

